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Amendments To The Specification:

Please replace the paragraph starting on page 6, line 10 with the following amended paragraph:

The control apparatus of the first braking device on the driving wheel has a controller 50. It will be driven, for example, when a cable rupture or another fault is found to exist in the braking system. An appropriate monitoring device is housed in the block 22. The output of the controller 50 is designated 52. The regulators 40, 42 have also integrated therein monitoring devices which if an error message is issued provide a signal to the controller 50 for an emergency stop. The controller 50 always generates a hard stop signal for the braking device 12 which signal, however, can come to an effect in a time delay via an appropriate ramp, shown at 54. A hard stop can also be made when other parameters measured cause a hard stop to be opportune. It is also imaginable here to connect the load-carrying wheel brakes 44, 46 for a hard stop. Output 52 further includes a delay, shown at 54. Regulators 40 has sensors 56, 58 and 60 associated with it, which respectively sense the lifting height of an industrial truck, the load on the industrial truck and the travel direction. Similarly, regulators 42 has sensors 64, 62, and 60 associated with it, which respectively sense the lifting height of an industrial truck, the load on the industrial truck and the travel direction. Lifting height sensor 56, load sensor 58 and travel direction sensor 60 are shown input to brake control device 18. Finally, brake 12 has a drive wheel 66 associated with it.